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Visibility-based optimal path and motion planning problems arise in many real-world situations. We begin with a few examples which will be used later to illustrate the application of the

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The material presented here may serve as a portion of an introductory course or seminar on visibility-based optimal path and motion planning problems with the objective of stimulating interest and further studies in this relatively new area.

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So far, we have considered various visibility-based optimization problems in which either the point-observers are stationary or free to move along certain admissible paths.

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